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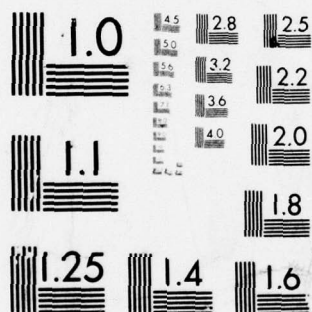
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Two-Dimensional Fluid Simulation of Relativistic Electron Beam-High Z Target Interactions

D. G. COLOMBANT and D. MOSHER

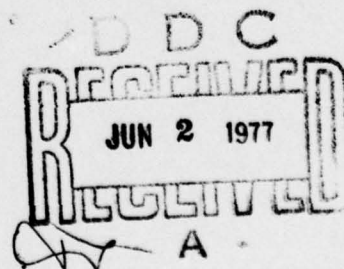
*Plasma Dynamics Branch
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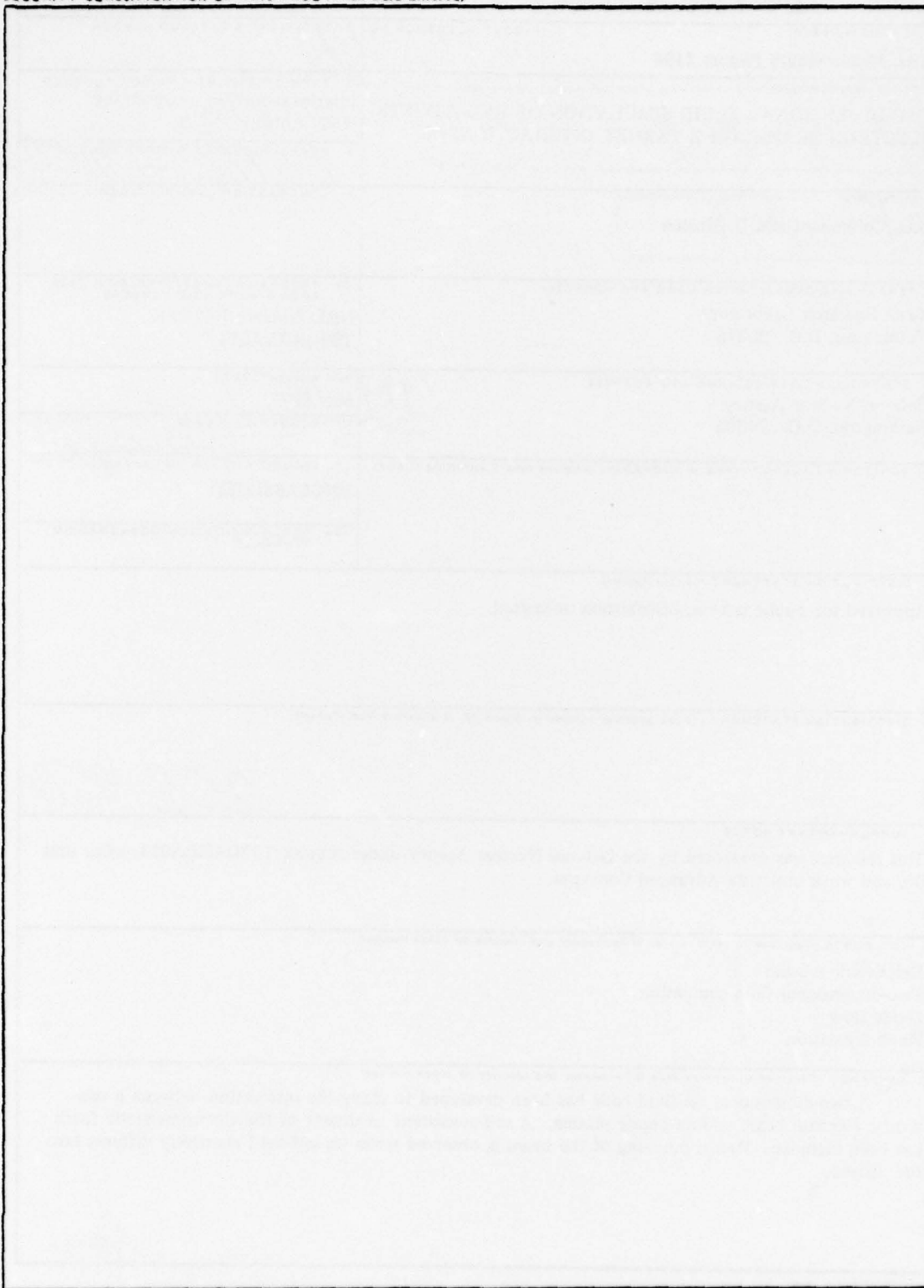
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TWO DIMENSIONAL FLUID SIMULATION OF RELATIVISTIC ELECTRON BEAM-HIGH Z TARGET INTERACTIONS

I. INTRODUCTION

Calculations of pinched flows in relativistic electron beam diodes have so far relied heavily on particle simulation codes.¹⁻³ However, another possible approach consists of treating the electron beam as a fluid along with the anode plasma. Both approaches might be complementary in the understanding of mechanisms taking place inside the diodes.

In particular, Refs. 2 and 3 have been highly successful in explaining the pinching of the electron beam by bootstrapping its way toward the axis of the diode, showing how anode ions and plasma aid in the pinch formation. However, these works make specific, simple assumptions concerning the electromagnetic fields and the motion of the anode plasma.

It is clear that a fully self-consistent two-dimensional model of a relativistic electron beam-plasma interaction is desired. In this present work, we report on the numerical study of such an interaction by means of a two-dimensional fluid model. In this first attempt, we have made simplifying assumptions (convenient for a fluid model) and in particular, it is assumed that the plasma is low enough in density to neglect beam-plasma collisions so that the electrons can be treated as

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cold. Calculations start when the self-field of the beam starts to diffuse into the plasma. It is desired to determine how charge-neutralization provided by the plasma causes the incident beam to pinch in the diffused magnetic field.

In Sec. II, a general model for the relativistic e-beam plasma interaction is presented as well as initial and boundary conditions. The general model includes collisions of the beam with the plasma. Simplified equations solved in the remainder of this study are then presented and their limits of application discussed. In Sec. III, the computational results obtained are displayed. In Sec. IV, conclusions are summarized and further steps are suggested in order to solve the full set of general equations.

II. MODEL EQUATIONS

Relativistic, collisional electron beam-plasma equations have been derived and reported by Mosher.⁴ They are presented here again for the sake of completeness. If n denotes the beam electron density, \underline{u} its fluid-flow velocity, $\langle \gamma \rangle$ the value of γ (the relativistic factor) averaged over the beam electron distribution function, α_e and α_i the effective values of $Z \ln \Lambda_e$ and $Z^2 \ln \Lambda_i$ for interaction with plasma electrons and ions respectively, then the beam fluid equations can be written:

$$\frac{\partial n}{\partial t} + \nabla \cdot n \underline{u} = 0, \quad (1)$$

$$\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} + \frac{1}{m_0 \langle \gamma \rangle n} \nabla \cdot \underline{\pi} + \frac{e}{m_0 \langle \gamma \rangle} \left[\underline{E} \cdot \left(\underline{I} - \frac{\underline{u} \underline{u}}{c^2} \right) + \underline{u} \times \underline{B} \right]$$

$$= - 4\pi n_i r_o^2 c (\alpha_e + 2 \alpha_i) \frac{\langle \gamma \rangle \underline{u}}{\langle p \rangle^3 / m_o^3 c^3} , \quad (2)$$

and

$$\frac{\partial \langle \gamma \rangle}{\partial t} + \underline{u} \cdot \nabla \langle \gamma \rangle + \frac{e}{m_o c^2} \underline{E} \cdot \underline{u} = - 4\pi n_i r_o^2 c \alpha_e \frac{\langle \gamma \rangle}{\langle p \rangle / m_o c} , \quad (3)$$

where π is a pressure term defined as

$$\underline{\pi} = \frac{n \langle (\underline{p} - \langle \underline{p} \rangle)(\underline{p} - \langle \underline{p} \rangle) \rangle}{m_o \langle \gamma \rangle} ,$$

and

$$\langle p \rangle = mc(\langle \gamma \rangle^2 - 1)^{1/2} .$$

Appropriate forms for π have been discussed.⁴ The plasma equations coupled to these beam equations are:

$$\frac{\partial n_i}{\partial t} + \nabla \cdot n_i \underline{v} = 0 , \quad (4)$$

$$m_i n_i \left(\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} \right) + \nabla p = \underline{j} \times \underline{B} , \quad (5)$$

$$\frac{\partial \mathcal{E}}{\partial t} + \underline{\nabla} \cdot [(\mathcal{E} + p) \underline{v}] + \underline{\nabla} \cdot \underline{q} = \underline{j} \cdot \underline{E} - P_R$$

$$+ 4\pi n_i r_o^2 c \alpha_e \frac{\langle \gamma \rangle_{nm} c^2}{(\langle \gamma \rangle^2 - 1)^{1/2}}, \quad (6)$$

where n_i is the plasma ion density, \underline{v} the plasma fluid velocity, p the plasma pressure ($= (1 + Z)n_i kT$), \mathcal{E} the total plasma energy density, and \underline{j} the plasma current. The following Maxwell equations close the above system when quasineutrality is assumed:

$$\underline{\nabla} \times \underline{E} = - \frac{\partial \underline{B}}{\partial t}, \quad (7)$$

$$\underline{\nabla} \times \underline{B} = 4\pi(\underline{j} - en\underline{v}). \quad (8)$$

The system of Eqs. (1) - (8) describes the full interaction of a relativistic electron beam with a plasma once the plasma-electron transport equations are included. Let us note at this point that the time-scales for the electron and ion dynamics are very different (of the order of 3 orders of magnitude) and constitute one of the major problems to the simultaneous solutions of these equations. Dealing with both scales in the same computer run would be costly and wasteful unless a quasi-static approach to solving the electron equations is attempted in order to eliminate the short time-step requirement imposed by the Courant condition. This is reasonable since relativistic electron transit times are much smaller than the time over which macroscopic quantities vary. Such a formulation is in development. Equations (1) - (8) can be

simplified depending on the region of the beam plasma interaction under investigation. In fact, the electron beam-anode plasma system can be separated into three regions. In the first region, the beam flows through a vacuum containing field-emitted ions from the anode⁵ and is governed by the action of space-charge electric and magnetic fields and the applied axial accelerating field. In this region, Eqs. (1) - (3) apply with the coupling term set equal to 0 and E determined from Poisson's equation. In Region II, the beam interacts collectively with a low density plasma with diffusion of the magnetic field determined by the plasma conductivity in that region. In Region III, the beam interacts collisionally with the high-density plasma produced near the anode surface. The full system of Eqs. (1) - (8) apply in that region where collisions dominate. However, the action of dynamic friction which broadens the beam energy distribution is difficult to determine without recourse to kinetic theory.^{6,7}

In this work, we limit consideration to Region II where both quasineutrality and no collisions can be assumed. In that region where collisions are not important but where the field diffuses, the full system of equations can be reduced to the following:

$$\frac{\partial n}{\partial t} + \nabla \cdot n \underline{\tilde{u}} = 0, \quad (9)$$

$$\frac{\partial \underline{\tilde{u}}}{\partial t} + \underline{\tilde{u}} \cdot \nabla \underline{\tilde{u}} + \frac{e}{m_0 \gamma} \left[\underline{\tilde{E}} \cdot \left(\underline{\tilde{I}} - \frac{\underline{\tilde{u}} \underline{\tilde{u}}}{c^2} \right) + \underline{\tilde{u}} \times \underline{\tilde{B}} \right] = 0, \quad (10)$$

$$\nabla \times \underline{\underline{E}} = - \frac{\partial \underline{\underline{B}}}{\partial t} , \quad (11)$$

$$\nabla \times \underline{\underline{B}} = 4\pi (\underline{\underline{j}} - en\underline{\underline{u}}) . \quad (12)$$

In these equations, it has been assumed that the ion dynamics is frozen and only the beam equations and Maxwell equations are solved for. The plasma conditions enter these equations through an assumed constant scalar conductivity

$$\underline{\underline{j}} = \sigma \underline{\underline{E}} .$$

Furthermore, it is assumed that the electron beam is cold (i.e. the pressure term is equal to 0) since the beam-plasma collisions are negligible. As a result, the energy of the beam shows only in kinetic form and remains unchanged (i.e. changes in electric potential inside the plasma $\ll \frac{m_0 c^2}{e}$) so that the beam energy equation is not required any more. Equations (11) - (12) can be shown to constitute the diffusion equation for the magnetic field. In Eq. (12), $\underline{\underline{j}}_b = - en\underline{\underline{u}}$ is the primary current and $\underline{\underline{j}} = \sigma \underline{\underline{E}}$ is the plasma current. Note that when $\underline{\underline{j}}_b = - \underline{\underline{j}}$, the total current is 0 and we have

$$\nabla \times \underline{\underline{B}} = 0 .$$

The initial and boundary conditions are the following. At $t = 0$ and $z = 0$ (which delimits the beginning of Region II), the beam front enters the low density anode plasma. In that plane, the magnetic field

is the self field of the beam, i.e., $B(r, 0, t) = B_0$ and remains so at all times. For $z > 0$, $B(r, z, 0) = 0$ so that initially the total current vanishes. This condition will in turn impose an electric field E_0 defined by

$$E_0 = - \eta n(r, 0, 0) u_z(r, 0, 0) ,$$

where u_z is given by the initial choice of γ and $\eta = \sigma^{-1}$. Care must be taken to make the velocity distribution of the beam consistent with the initial electric field in the plasma and so, initially we solve Eq. (13) for γ

$$\frac{d\gamma}{dz} = - \frac{E_0}{m_0 c^2} . \quad (13)$$

From the continuity equation, it follows that

$$n(r, z, 0) = \frac{n(r, 0, 0) u_z(r, 0, 0)}{\sqrt{1 - \gamma(z)^{-2}}} .$$

The initial electron beam density distribution in the radial direction is chosen as a square profile whose edge has been smoothed slightly for computational purposes. The vacuum density outside the beam has been chosen to be 10^{-4} times the initial beam density for the present calculations, but it can be changed easily. The radial velocity u_r has been taken equal to 0 everywhere at $t = 0$. The radial electric field is assumed to be 0 at $z = L$ where L delimits the end of Region II. This condition results from the assumption that the anode is an equipotential plane.

Another characteristic of the model is that σ , the only quantity characterizing the plasma in the equations solved, is assumed to be constant, corresponding to an isothermal plasma in Region II. For practical reasons, σ was chosen so that complete diffusion of the magnetic field occurs after a few hundreds of time steps. This requirement corresponded to a very low temperature of the plasma (10^{-1} eV and below). In reality, σ is determined from the plasma temperature achieved by electron-beam heating in Eq. (6).

Numerically, the grid has been chosen inhomogeneous in the r -direction in order to increase the numerical resolution near the axis. The spatial step goes from 0.1 cm near the axis to 8.6 cm in the vacuum. Equations (9) and (10) are solved explicitly using FCT⁸ whereas the magnetic field diffusion equation is solved implicitly. The time-step is controlled by the Courant condition based on the electron fluid motion.

III. RESULTS

The case presented below corresponds to the following input parameters:

Beam radius	5 cm
Beam current	1 MA
Beam axial velocity	$\beta_z = \frac{v_z}{c} = 0.943$ ($\gamma = 3$)
Length of Region II	0.5 cm

Figures 1 and 2 show density contours at $t = \tau_{\text{diff}}/2$ and $t = 2 \tau_{\text{diff}}$ respectively where

$$\tau_{\text{diff}} = \frac{4\pi\sigma L^2}{c^2}.$$

The initial density was set equal to 2.8×10^{12} and remains so in the plane $z = 0$. Figure 1 shows pinch formation occurring obliquely with respect to the diode axis. The maximum density at the time of Fig. 1 is 2×10^{13} , almost an order of magnitude above the initial density. Figure 2 shows strong pinching on the axis near $z = L$. The density is then almost 200 times the initial density.

Figures 3 and 4 show e-beam fluid streak lines at the same times as Figs. 1 and 2. The pinching is seen to form closer to the end of Region II as the radius decreases. As time develops, this remains true but the pinching recedes toward the cathode. Outside the pinching region, we note areas where deconfining forces dominate temporarily.

The magnetic field at $r = 3.21$ cm is shown in Fig. 5. It is clear from this graph that the field excluded initially progressively fills the plasma in Region II. By $t = 2 \tau_{\text{diff}}$, the field has diffused entirely into the anode plasma.

Figures 6 and 7 show radial profiles of the magnetic field at $t = \tau_{\text{diff}}/2$ and $t = 2 \tau_{\text{diff}}$. At $z = 0$, the self-field of the beam is shown, increasing linearly with r up to the beam boundary and then decaying as $1/r$ in the vacuum. Departures from the linear rise indicates a higher current density near the axis, corresponding to pinching. This pinching is shown very clearly at $z = L$ in Fig. 7. The beam axial

velocity is down by more than a factor of 10 in this area. One of the results found with our model is that no steady state has been reached after $2 \tau_{\text{diff}}$ and the flow remains unsteady in all parts of the Region II of the diode under consideration.

IV. CONCLUSIONS

In this work, we have described the electromagnetic interaction of a relativistic e-beam with an anode plasma. We have shown the solution in the low-density plasma region where fields diffuse but where collisions are unimportant. We have found that the beam pinches in such a configuration but that the solution does not reach a steady-state for the time-scales involved in this study. This is in part due to the fact that the plasma does not respond to beam-heating so that magnetic diffusion continues to larger values of z . If the plasma was allowed to heat, high temperature in the pinch would stop the diffusion. In any case, the pinching observed in the regime under investigation is significant because it shows that a low density plasma in front of the anode can cause its formation.

The discussed solution constitutes a first step in the solution of a full beam-plasma dynamic interaction. The relativistic e-beam fluid equations have been tested as well as the magnetic field diffusion equation. Addition of a pressure term to the beam equations and collisional coupling to a plasma system of equations remain to be done. In view of the length of the calculations required for the e-beam dynamics when performed on an electron time-scale, this study strongly suggests that the beam equations be solved implicitly if coupling to a much slower

dynamics is planned as a next step. Nevertheless, this study has provided interesting results of its own and pointed out causes of eventual problems in an implicit treatment.

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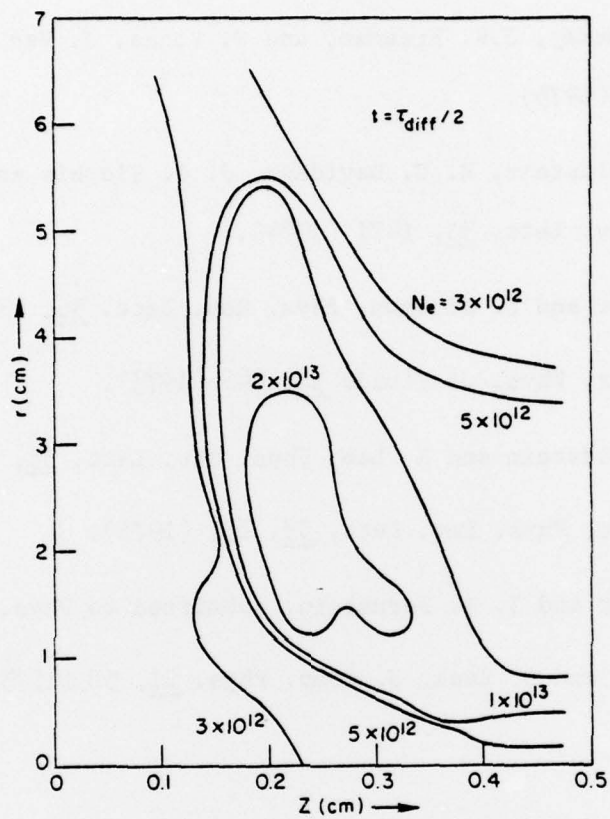


Fig. 1 — Electron density contours at $t = \tau_{diff}/2$ where τ_{diff} is the characteristic magnetic field diffusion time

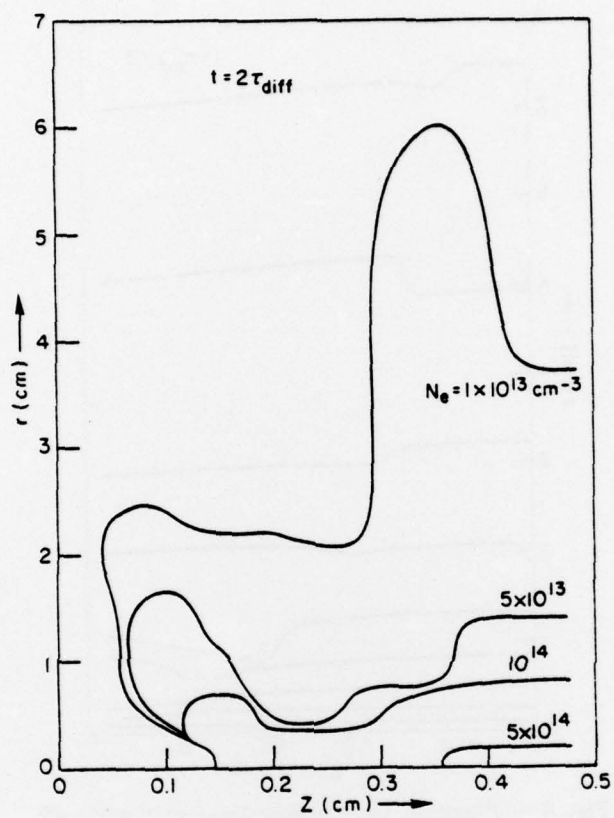


Fig. 2 — Electron density contours at $t = 2 \tau_{\text{diff}}$

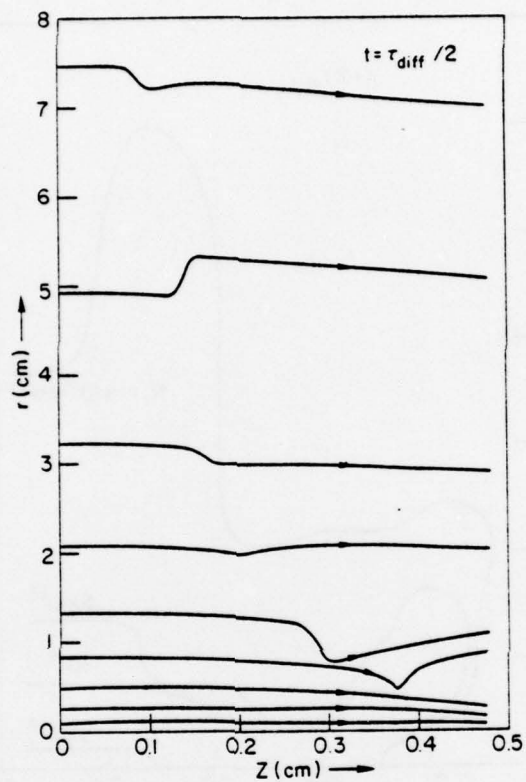


Fig. 3 — Electron fluid streak lines at $t = \tau_{diff}/2$

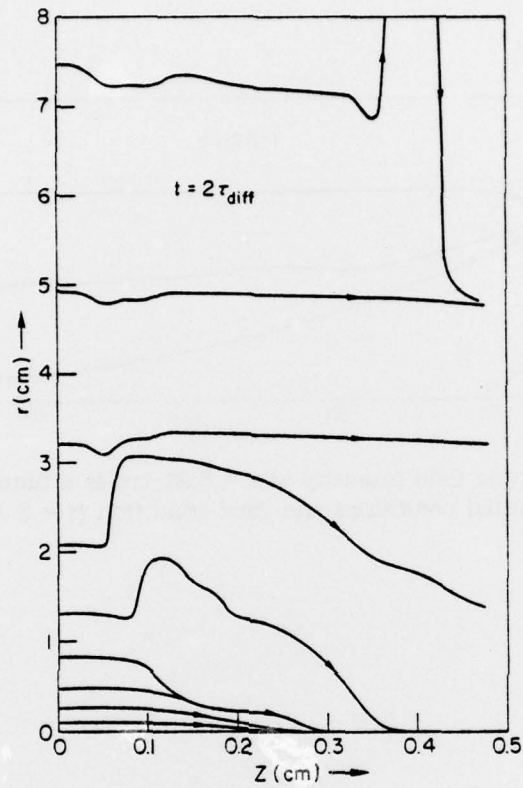


Fig. 4 — Electron fluid streak lines at $t = 2 \tau_{\text{diff}}$

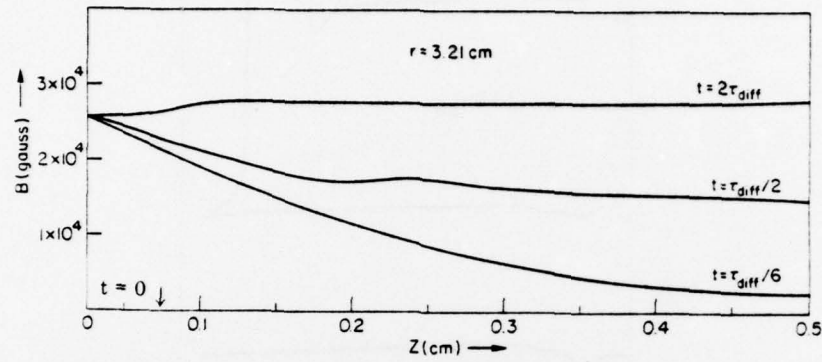


Fig. 5 — Magnetic field intensity at $r = 3.21$ cm as a function of time. Note initial conditions and final condition ($t = 2 \tau_{diff}$).

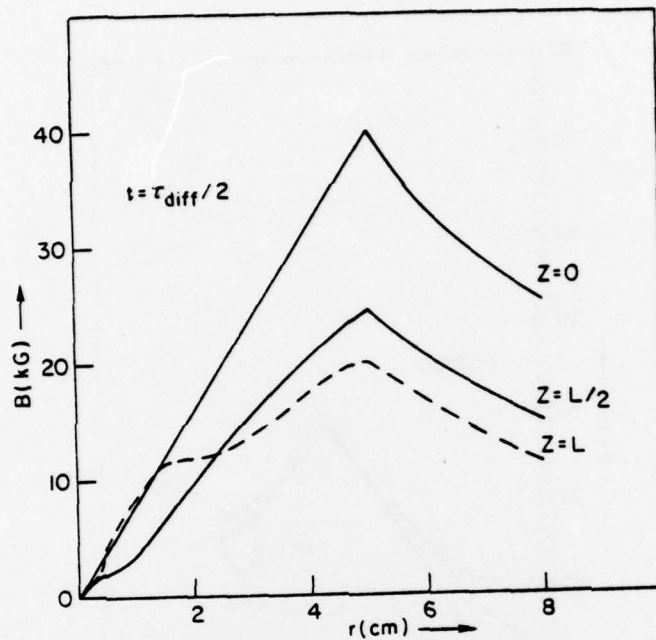


Fig. 6 — Magnetic field radial profiles at $t = \tau_{diff}/2$ at various z

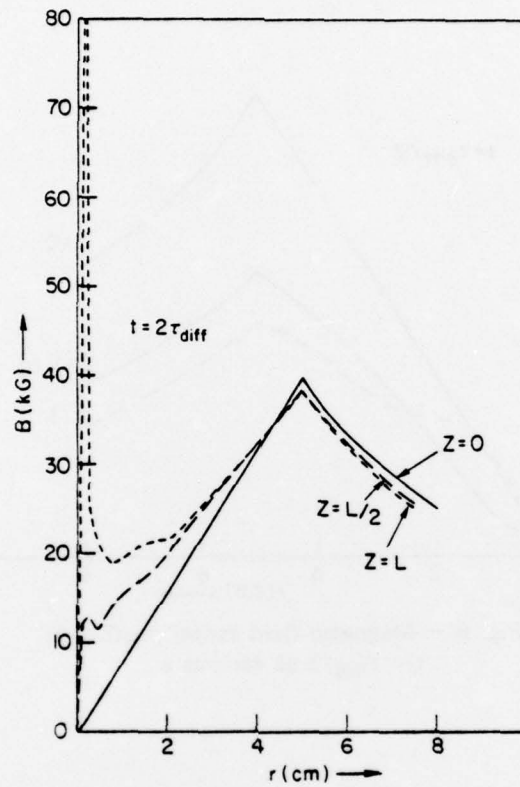


Fig. 7 — Magnetic field radial profiles at $t = 2 \tau_{\text{diff}}$ at various z . Note that at $z = 0$, the B field radial profile does not change. Also, large values of field near axis indicate pinching.

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